



R Package iglm: Regression under Interference in Connected Populations

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Structure

Interference in Connected Populations

Scalable Models

Interpretable Models

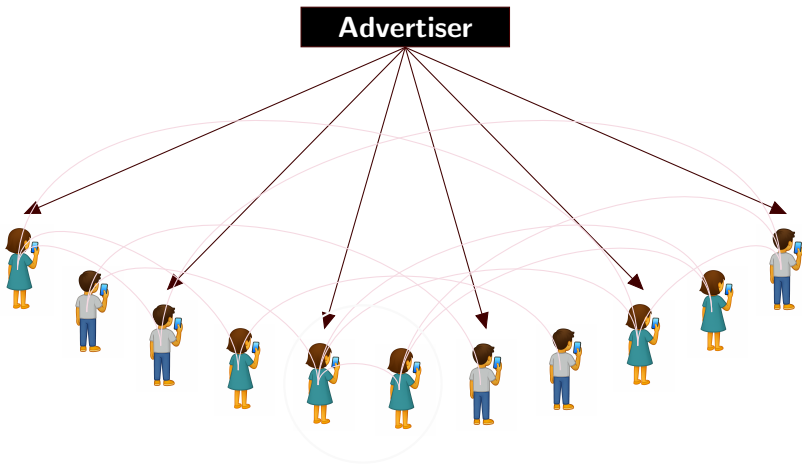
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Theoretical Guarantees

Hate Speech on X

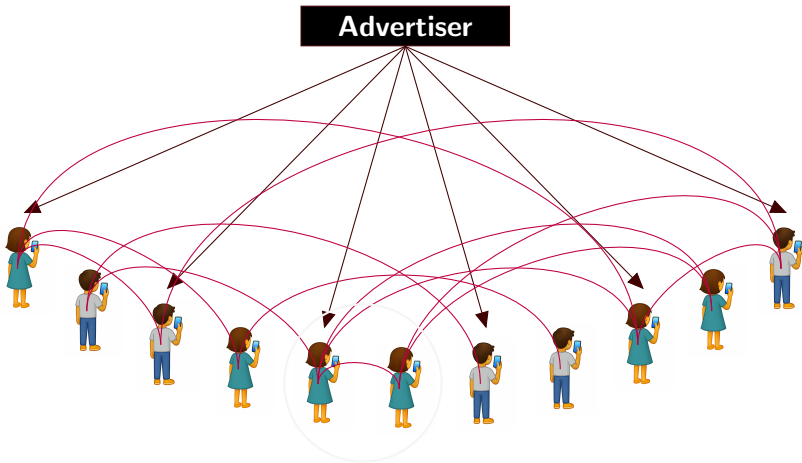
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Example



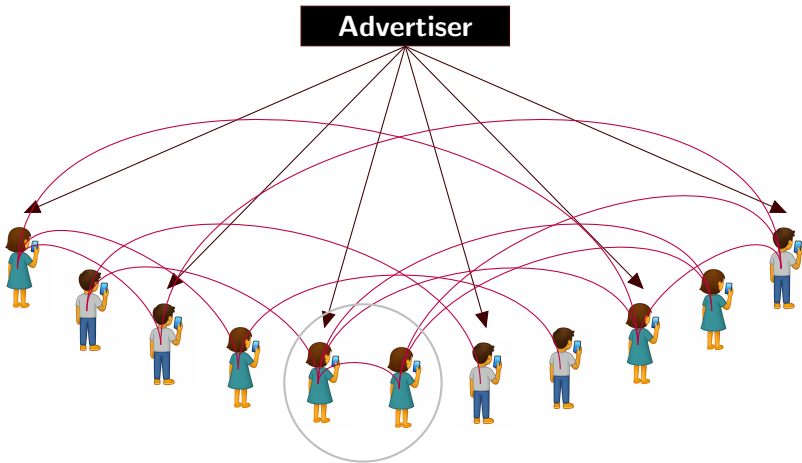
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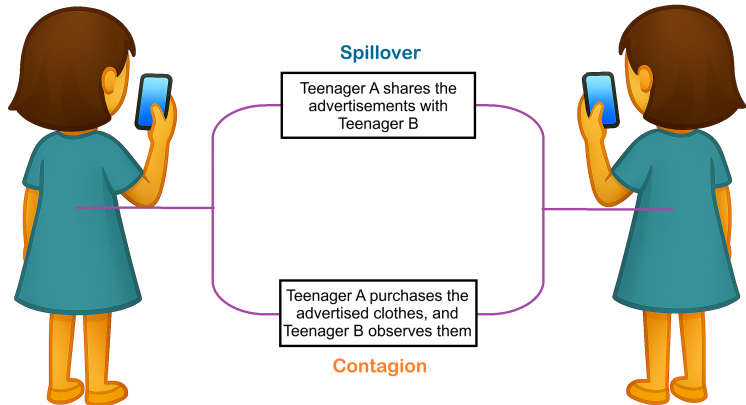


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Example



Interference

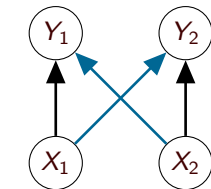
Population of $N = 2$ units 1, 2 with connection $Z_{1,2} = 1$:



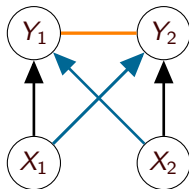
Predictors X_1, X_2 and outcomes Y_1, Y_2 of units 1, 2:



Main Effect



+ Effect of Spillover



+ Effect of Contagion

An empirical study by Lee & Ogburn (2021) highlights the consequences of ignoring dependence among outcomes due to contagion and other real-world processes in connected populations.

Interference

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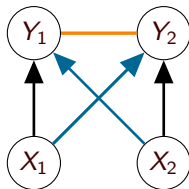
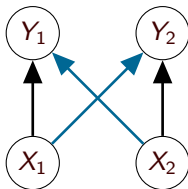
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- ▶ Conditional models of connections $\mathbf{Z} \mid \mathbf{X}$ (e.g., ERGMs):
Who connects with whom?
- ▶ Conditional models of outcomes $\mathbf{Y} \mid (\mathbf{X}, \mathbf{Z})$ (e.g., ALAAMs):
Who influences whom?
- ▶ Combining models of $\mathbf{Z} \mid \mathbf{X}$ and $\mathbf{Y} \mid (\mathbf{X}, \mathbf{Z})$ assumes that connections $\mathbf{Z}$ are not affected by outcomes $\mathbf{Y}$.
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 - neither models nor methods scale from small to large N ;
 - lack theoretical guarantees: we do not know whether the error of estimation decays as N increases, and at which rate.

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Regression Under Interference

Introduce comprehensive regression framework for studying relationships among attributes ($\mathbf{X}$, $\mathbf{Y}$) and connections $\mathbf{Z}$:

- ▶ **Scalable models**, capturing heterogeneity along with dependence among $(\mathbf{X}, \mathbf{Y})$ and $\mathbf{Z}$ in large populations.
- ▶ **Interpretable models**, based on extensions of Generalized Linear Models (GLMs) to dependent $(\mathbf{X}, \mathbf{Y})$ and $\mathbf{Z}$.
- ▶ **Scalable methods**, based on convex optimization of pseudolikelihoods, implemented by a divide and conquer approach using minorization-maximization (MM) methods.
- ▶ **Provable theoretical guarantees**, based on a single observation of dependent random variables $(\mathbf{X}, \mathbf{Y})$ and $\mathbf{Z}$.
- ▶ **Software**: R package `glm`, which extends R functions `glm()` and `glm2()` to regression under interference and contains a `glmm` function, and other R scripts and R packages.

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Connected population of $N \geq 2$ units:

- ▶ one or more binary, count-, or real-valued predictors X_i : e.g., covariates or treatment assignments;
- ▶ binary, count-, or real-valued responses or outcomes Y_i ;
- ▶ binary, count-, or real-valued connections $Z_{i,j}$, directed or not.

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Scalable Models

How to extend GLMs for independent attributes (X_i, Y_i) to dependent attributes (X_i, Y_i) and connections $Z_{i,j}$?

$$f_{\theta}(\mathbf{x}, \mathbf{y}, \mathbf{z}) \propto \prod_{i=1}^N a_{\mathcal{X}}(x_i) a_{\mathcal{Y}}(y_i) e^{\theta_g^{\top} g_i(\mathbf{x}_i, y_i)} \quad \text{GLM}$$
$$\times \prod_{i < j}^N a_{\mathcal{Z}}(z_{i,j}) e^{\theta_h^{\top} h_{i,j}(\mathbf{x}_i, y_i, y_j, \mathbf{z})} \quad \text{Interference}$$

- ▶ Models with complex dependence can be constructed using two simple building blocks: g_i and $h_{i,j}$.
- ▶ The functions $h_{i,j}$ can induce dependence among outcomes Y_i and connections $Z_{i,j}$.
- ▶ To build scalable models that can accommodate small and large populations, each unit i has a (known) neighborhood $\mathcal{N}_i$, which can affect i 's attributes (X_i, Y_i) and connections $Z_{i,j}$.

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If g_i and $h_{i,j}$ are coordinatewise affine,

- ▶ conditionals of predictors X_i can be represented by GLMs;
- ▶ conditionals of outcomes Y_i can be represented by GLMs;
- ▶ conditionals of connections $Z_{i,j}$ can be represented by GLMs.

Thus, results can be interpreted along the lines of GLMs.

Background: GLMs

GLMs extend linear regression

$$Y_i = \alpha_y + \beta_{x,y} x_i + \epsilon_i$$

to binary, count-, and continuous outcomes Y_i :

- ▶ conditional distribution of outcome Y_i depends on the nature of Y_i and is an exponential family: e.g., Bernoulli (binary), Poisson (count), Gaussian (continuous);
- ▶ conditional expectation of outcome Y_i is either a linear or nonlinear function of a linear predictor: e.g., $\alpha_y + \beta_{x,y} x_i$.

Example: continuous outcome $Y_i \in \mathbb{R}$

Linear regression:

1. *Conditional distribution of outcome Y_i : $N(\mu_i(\eta_i), \psi)$*
2. *Conditional expectation of outcome Y_i :*

$$\mu_i(\eta_i) = \eta_i$$

where

$$\eta_i = \alpha_Y + \beta_{X,Y} x_i$$

capturing the effect of x_i on Y_i .



Linear regression assumes that the outcome Y_i of unit i is not affected by the outcome Y_j of any other unit j .

Example: count-valued outcome $Y_i \in \{0, 1, \dots\}$

Poisson regression:

1. *Conditional distribution of outcome Y_i : $\text{Poisson}(\mu_i(\eta_i))$*
2. *Conditional expectation of outcome Y_i :*

$$\mu_i(\eta_i) = \exp(\eta_i)$$

where

$$\eta_i = \alpha_Y + \beta_{X,Y} x_i$$

capturing the effect of x_i on Y_i .



Poisson regression assumes that the outcome Y_i of unit i is not affected by the outcome Y_j of any other unit j .

Example: binary outcome $Y_i \in \{0, 1\}$

Logistic regression:

1. *Conditional distribution of outcome Y_i :* Bernoulli($\mu_i(\eta_i)$)
2. *Conditional expectation of outcome Y_i :*

$$\mu_i(\eta_i) = \frac{\exp(\eta_i)}{1 + \exp(\eta_i)}$$

where

$$\eta_i = \alpha_y + \beta_{x,y} x_i$$

capturing the effect of x_i on Y_i .



Logistic regression assumes that the outcome Y_i of unit i is not affected by the outcome Y_j of any other unit j .

Example of g_i and $h_{i,j}$

Models with complex dependence can be constructed using two simple building blocks:

$$g_i := \begin{pmatrix} y_i \\ x_i y_i \end{pmatrix} \quad \begin{pmatrix} \text{intercept } \alpha_y \\ \text{effect } \beta_{x,y} \text{ of } x_i \text{ on } Y_i \end{pmatrix}$$

$$h_{i,j} := \begin{pmatrix} \mathbf{e}_{i,j} z_{i,j} \\ -(1 - c_{i,j}) z_{i,j} \log N \\ d_{i,j}(\mathbf{z}) z_{i,j} \\ c_{i,j} (x_i y_j + x_j y_i) z_{i,j} \\ c_{i,j} y_i y_j z_{i,j} \end{pmatrix} \quad \begin{pmatrix} \text{degree heterogeneity } \alpha_{z,i}, \alpha_{z,j} \\ \text{sparsity } \lambda \\ \text{local transitivity } \gamma_{z,z} \\ \text{spillover } \gamma_{x,y,z} \\ \text{contagion } \gamma_{y,y,z} \end{pmatrix}$$

where the dimension of $\boldsymbol{\theta} := (\boldsymbol{\theta}_g, \boldsymbol{\theta}_h) \in \mathbb{R}^{N+6}$ increases with N .

Example: continuous outcome $Y_i \in \mathbb{R}$

Let

$$a_Y(y_i) := \frac{1}{\sqrt{2\pi}\psi} \exp\left(-\frac{y_i^2}{2\psi}\right) \mathbb{I}(y_i \in \mathbb{R})$$

1. *Conditional distribution of outcome Y_i : $N(\mu_i(\eta_i), \psi)$*
2. *Conditional expectation of outcome Y_i :*

$$\mu_i(\eta_i) = \eta_i$$

where

$$\begin{aligned} \eta_i = & \alpha_Y + \beta_{X,Y} x_i + \gamma_{X,Y,Z} \sum_{j: N_i \cap N_j \neq \emptyset} x_j z_{i,j} \\ & + \gamma_{Y,Y,Z} \sum_{j: N_i \cap N_j \neq \emptyset} y_j z_{i,j} \end{aligned}$$

capturing **spillover** and **contagion**.

Example: count-valued outcome $Y_i \in \{0, 1, \dots\}$

Let

$$a_Y(y_i) := \frac{1}{y_i!} \mathbb{I}(y_i \in \{0, 1, \dots\})$$

1. *Conditional distribution of outcome Y_i :* $\text{Poisson}(\mu_i(\eta_i))$
2. *Conditional expectation of outcome Y_i :*

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where

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Pseudo-loglikelihood:

$$\begin{aligned}\ell(\boldsymbol{\theta}; \mathbf{x}, \mathbf{y}, \mathbf{z}) &:= \sum_{i=1}^N \log f_{\boldsymbol{\theta}}(x_i \mid \text{others}) \\ &+ \sum_{i=1}^N \log f_{\boldsymbol{\theta}}(y_i \mid \text{others}) \\ &+ \sum_{i < j}^N \log f_{\boldsymbol{\theta}}(z_{i,j} \mid \text{others})\end{aligned}$$

where $\boldsymbol{\theta}$ is the vector of all weights.



Conditionals of X_i , Y_i , and $Z_{i,j}$ are tractable (e.g., Normal, Poisson, Bernoulli).

Divide and Conquer

Partition the parameter vector $\boldsymbol{\theta} := (\boldsymbol{\theta}_1, \boldsymbol{\theta}_2) \in \mathbb{R}^{N+6}$ into

► $\boldsymbol{\theta}_1 := (\alpha_{z,1}, \dots, \alpha_{z,N}) \in \mathbb{R}^N$

► $\boldsymbol{\theta}_2 := (\alpha_y, \beta_{x,y}, \gamma_{z,z}, \gamma_{x,y,z}, \gamma_{y,y,z}, \lambda) \in \mathbb{R}^6$

and partition the negative Hessian of ℓ in accordance:

$$-\nabla_{\boldsymbol{\theta}}^2 \ell(\boldsymbol{\theta}; \mathbf{y}, \mathbf{z}) \quad := \quad \begin{pmatrix} \mathbf{A}(\boldsymbol{\theta}) & \mathbf{B}(\boldsymbol{\theta}) \\ \mathbf{B}(\boldsymbol{\theta})^\top & \mathbf{C}(\boldsymbol{\theta}) \end{pmatrix}$$



The block $\mathbf{A}(\boldsymbol{\theta}) \in \mathbb{R}^{N \times N}$ contains N^2 elements.

Divide and Conquer with MM

Iterate:

Step 1: Given $\theta_2^{(t)}$, find $\theta_1^{(t+1)}$ such that

$$\ell(\theta_1^{(t+1)}, \theta_2^{(t)}; \mathbf{y}, \mathbf{z}) \geq \ell(\theta_1^{(t)}, \theta_2^{(t)}; \mathbf{y}, \mathbf{z})$$

Step 2: Given $\theta_1^{(t+1)}$, find $\theta_2^{(t+1)}$ such that

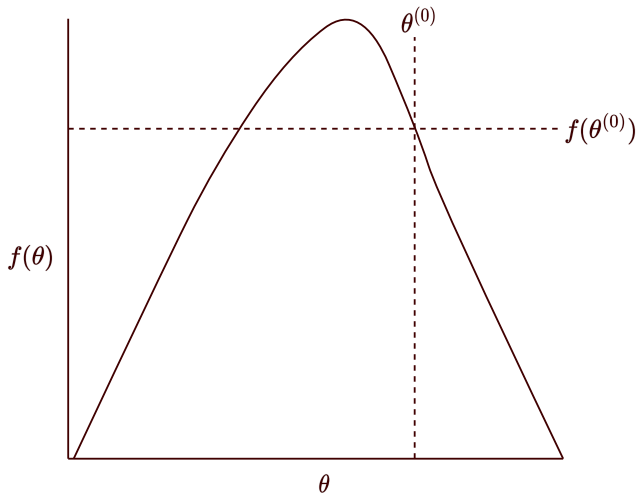
$$\ell(\theta_1^{(t+1)}, \theta_2^{(t+1)}; \mathbf{y}, \mathbf{z}) \geq \ell(\theta_1^{(t+1)}, \theta_2^{(t)}; \mathbf{y}, \mathbf{z})$$

Step 1 is implemented by a MM algorithm, replacing the inverse Hessian of ℓ (cost: $O(N^3)$) by a constant matrix (cost: $O(N)$).

Step 2 is implemented by a NR algorithm.

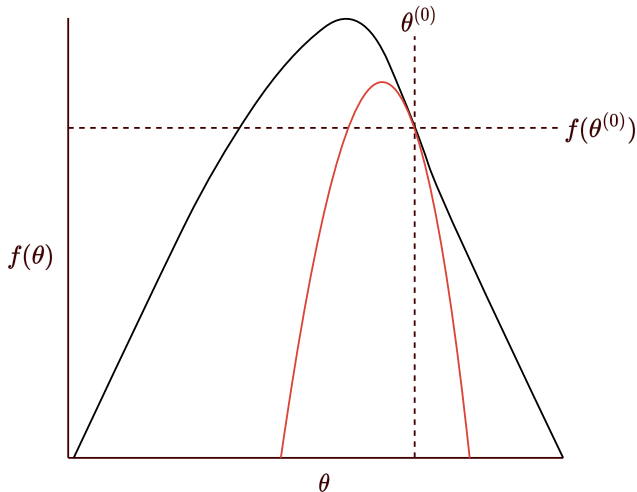
MM: Minorize-Maximize

Consider a generic objective function $f : \mathbb{R} \mapsto \mathbb{R}$:



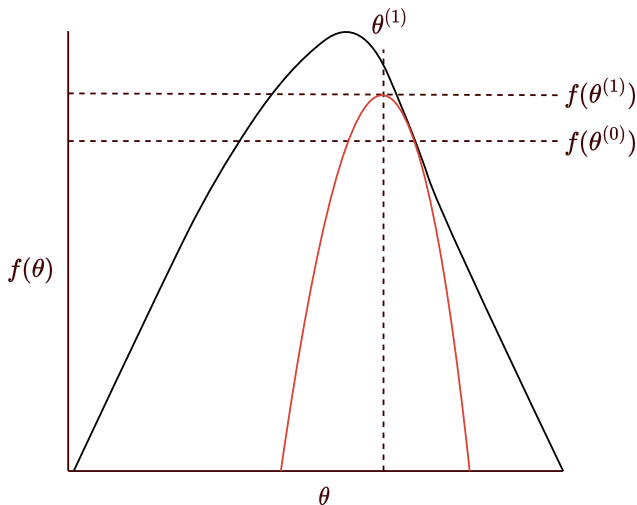
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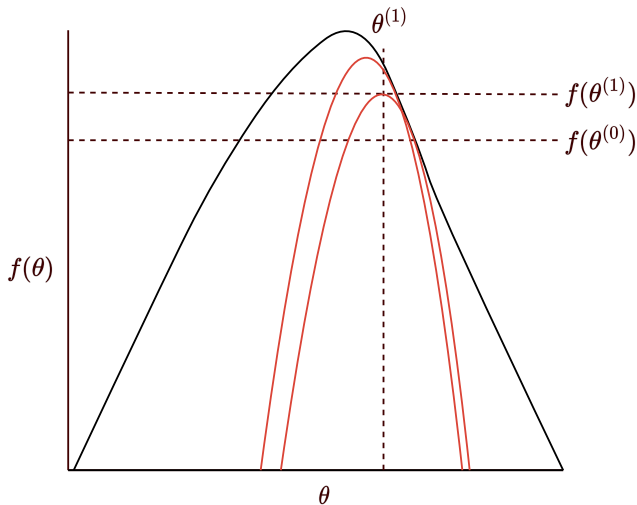
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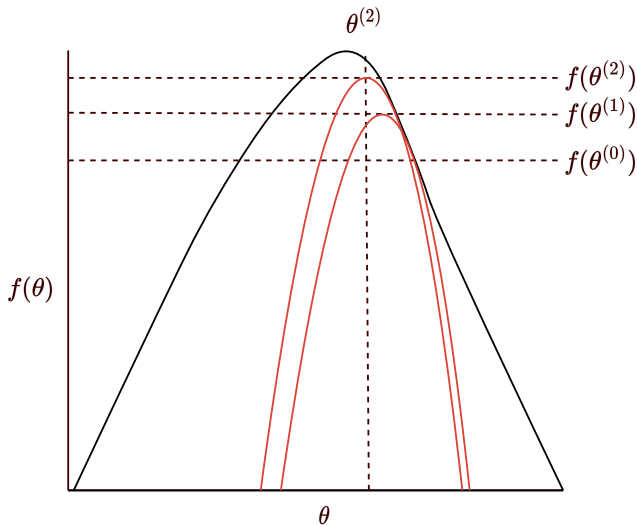
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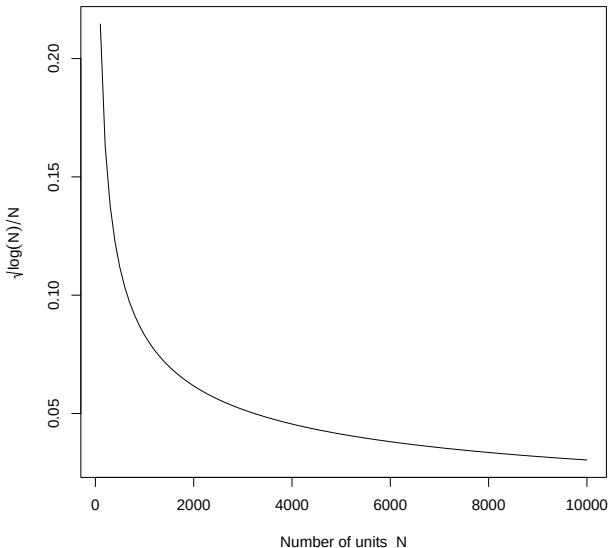
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A careful mathematical argument reveals that the error of estimation decays at rate $\sqrt{\log(N)/N}$ in the example model:

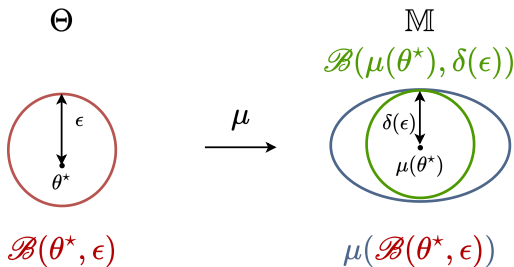


Peeking Under the Hood



Lemma 1 of S & S (Annals of Statistics 2026)

$$\frac{\epsilon}{\sup_{\theta \in \mathcal{B}(\theta^*, \epsilon)} \|\mathcal{I}(\theta)^{-1}\|} \leq \delta(\epsilon)$$



Lemma 1 relates

- ▶ the radius ϵ of balls in Θ (unobservables: weights)
 - ▶ the radius $\delta(\epsilon)$ of balls in $\mathbb{M}$ (observables: sums of g_i , $h_{i,j}$),
- helping establish the rate at which the error of estimation decays.

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Data shared by B. Desmarais: 109,974 posts by $N = 2,191$ U.S. state legislators between June 6, 2020 and January 6, 2021:

- ▶ $x_{i,1} = 1$ if legislator i is Republican and is 0 otherwise,
- ▶ $Y_i = 1$ if legislator i made at least one post with hate speech and is 0 otherwise based on Large Language Models (LLMs),
- ▶ $Z_{i,j} = 1$ if legislator i mentioned or retweeted legislator j in a tweet and is 0 otherwise,
- ▶ $\mathcal{N}_i$ is the set of legislators followed by legislator i , i.e., the set of legislators who can influence i .

Other predictors: gender ($x_{i,2}$), race ($x_{i,3}$), and state ($x_{i,4}$).

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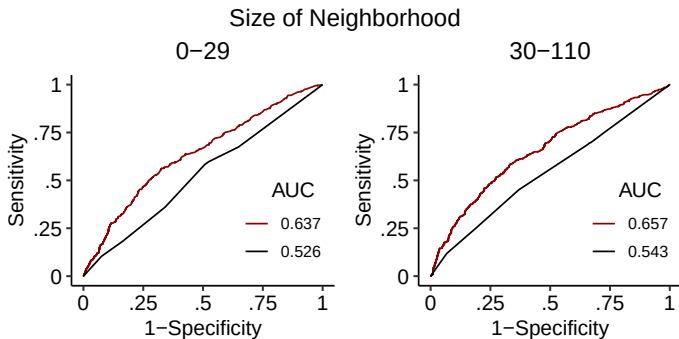
Weight	Estimate	S.E.	Weight	Estimate	S.E.
α_Y	-.893	.143	$\gamma_{Z,Z,1}$	.604	.037
$\beta_{X,Y,1}$	-.257	.159	$\gamma_{Z,Z,2}$	2.57	.031
$\beta_{X,Y,2}$	-.034	.117	$\gamma_{X,Z,1}$	.035	.005
$\beta_{X,Y,3}$	.069	.095	$\gamma_{X,Z,2}$	.236	.015
$\gamma_{Y,Z}$	-.007	.055	$\gamma_{X,Z,3}$	.756	.028
$\hat{\gamma}_{X,Y,Z}$	.038	.014	$\gamma_{X,Z,4}$	4.729	.041
			λ	.184	.005

The positive sign of $\hat{\gamma}_{X,Y,Z} = .038$ suggests that the more Republicans interact with legislator i , the higher is the conditional probability of the event that legislator i uses offensive text in a post, holding everything else constant.

Hate Speech on X

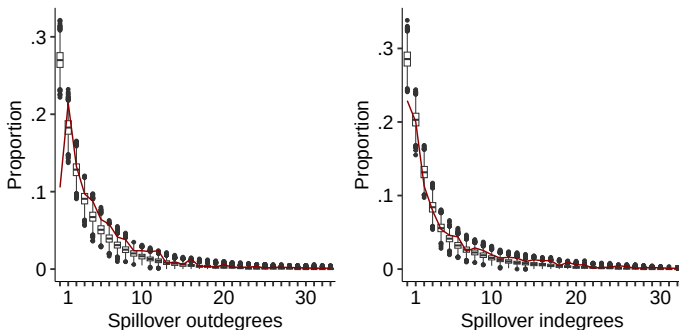
Compare model-based predictions:

- ▶ $Y_i \mid \mathbf{X}_i = \mathbf{x}_i$: logistic regression
- ▶ $Y_i \mid (\mathbf{X}, \mathbf{Y}_{-i}, \mathbf{Z}) = (\mathbf{x}, \mathbf{y}_{-i}, \mathbf{z})$



Hate Speech on X

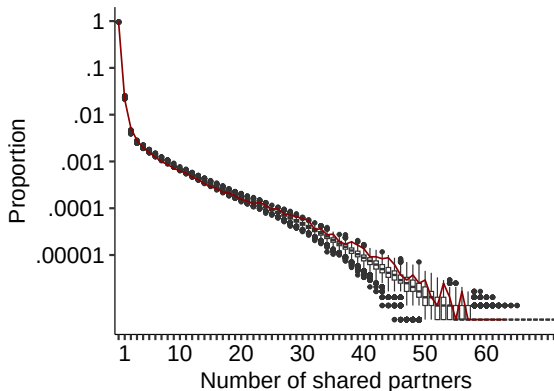
Model-based predictions of spillover in- and outdegrees of U.S. legislators in the subnetwork with i being Republican, j using offensive language, and the neighborhoods of i and j overlapping:



By construction, the connections in the subnetwork act as potential channels of spillover.

Hate Speech on X

Model-based predictions of the shared partners distribution of the network of repost and mention interactions of U.S. legislators:



Capturing closure in the network of U.S. legislators.

References

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